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Semi-Supervised Z-stack segmentation using Random Forest Classifier

Mini Thesis

*In the program Advanced Optical Technologies*

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Zusammenfassung

Biologie ist eine quantitative Wissenschaft, die eine erhebliche Menge an Daten benötigt, um eine bestimmte Hypothese zu beweisen. Bilder von Zellen und Geweben sind die große Datenquelle, aber Daten allein reichen nicht aus, sie müssen verbessert, verarbeitet, analysiert und quantifiziert werden, um aussagekräftige Erkenntnisse zu gewinnen.

Eines der Werkzeuge, die bei der Verarbeitung der Daten helfen, sind Deep Neural Networks. Diese Netzwerke können hervorragende Ergebnisse bei Aufgaben wie der Bildklassifizierung und -segmentierung zeigen, erfordern jedoch eine große Menge an Trainingsbeispielen, um daraus zu lernen. Die Bildklassifizierung lässt sich recht einfach von Hand beschriften, dies ist jedoch bei der semantischen Segmentierung nicht der Fall. Die manuelle Beschriftung zur Bildsegmentierung erfordert viel Zeit, um die Umrisse für jeden Pixelbereich zu zeichnen und ihnen Beschriftungen zuzuordnen. Die Hauptidee dieser Arbeit ist es, einen halbautomatischen unüberwachten Zellsegmentierungsalgorithmus für die 3D-Zellsegmentierung zu finden.

Abstract

Biology is a quantitative science, that requires a significant amount of data to prove a certain hypothesis. Images of cells and tissues are the great source of data, but data itself is not enough, it must be enhanced, processed, analyzed, and quantified to get meaningful insights.

One of the tools that helps to process the data are Deep Neural Networks. These networks can show outstanding results in tasks like image classification and segmentation, although require a huge amount of training samples to learn from. Image classification is quite easy to label by hand, but that's not the case for semantic segmentation. Manual labeling for image segmentation requires a lot of time to draw the outline for each pixel area and assign labels to them. The main Idea of this thesis is to find semi-automated unsupervised cell segmentation algorithm for 3D cell segmentation.

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Abbreviations

|  |  |
| --- | --- |
| CLSM | Confocal Laser Scanning Microscope |
| CNN | Convolutional Neural Network |
| H&E | Hematoxylin and Eosin |
| RF | Random Forest |
| DTC | Decision Tree Classifier |
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# Introduction

Getting insights from volumetric biological data is a sophisticated task, that depend upon the modality that was used to acquire images, sample preparation and software that will quantify the raw data and give the meaningful results, that can be interpret. Each month new software algorithms are published, serving new approaches for segmentation and classification tasks, but most of them are Deep Learning algorithms, that require a gigantic human labeled data. Human time is expensive, hence an assistance for labeling would be a helping hand to reduce time for labeling. In this Thesis classical machine learning approach using Random Forest (RF) will be explained and utilized for human immune cells segmentation.

# State of the Art

## Imaging in Medical Diagnostics

### Histopathology H&E

Histopathology is the science of microscopic image analysis. It is always performed by specially trained personnel, that examines thin tissue or cell samples under the microscope. This personnel search for the abnormalities in tissue or cell structure based on the color and shape. Usually, samples don’t have any color and mostly invisible under the brightfield microscope. Due to that it is often required to perform staining – a procedure to dye transparent tissue with specific chemicals. Theses chemicals’ specificity allows for different chemicals bind to different cells, allowing to distinguish between tissue types.

One of the most widely used chemicals is the Hematoxylin and Eosin (H&E) [1] it consists of two main chemicals:

* Hematoxylin – blue-purple dye which binds to nucleic acids. Mainly stains nuclei of cells
* Eosin – pink dye which stains proteins. Can be observed in cytoplasm and extracellular matrix

The combination of these colors in tissue helps histopathologists to identify anomalies such as cancer and others.

Histopathologists do not only use microscopes directly, but they also often prefer to have a wider perspective on the sample by means of digital images. These images are mostly two-dimensional. But this is not always the case.

### Volumetric Data

To receive more data from tissue it is required to record volumetric images also known as Z-stacks or stacks. This is a three-dimensional image with multiple color channels. It can be expressed as:

Stack allows to see the cells in volume which is oftentimes necessary. For example, direct observation of skin cells together with immune cells lying under the skin layer like in [2].

## Motivation

In biological research it is highly important to understand, prepare and detect a specimen to conduct an experiment. Data acquired for this thesis was taken from a Human colon tissue using Confocal Laser Scanning Microscope.

### Human immune cells in colon tissue

Immune cells are present in the human body. For example, macrophages are present in every tissue, and patrolling for bacterial infection or dead cells. Once a case of infection in human colon tissue happens, macrophages start to fight infection and call other immune cells like Neutrophils for the help. Neutrophils are entering the infected zone from blood vessels to kill the cause of inflammation. If first line of defense is not effective against the infection, then a dendritic cell will start to gather the information about the invader to deliver it to the T-cells in lymphatic system. Once dendritic cells will find the T-cell that recognizes this type of infection, T-cell is activated and start to divide to reach 2 goals. 1st goal is to deliver macrophages to boost the performance of macrophages on site. 2nd goal is to activate B-cells that will start to produce antibodies against infection.

High concentration of immune cells is concrete evidence of inflammation in human colon tissue. In order to detect presence, quality and quantity of immune cells in tissue techniques like CLSM might be very useful.

### Confocal Laser Scanning Microscope

Confocal Laser Scanning Microscope is another microscopic modality a kind of light optical microscopy, which has significant contrast and spatial resolution compared to classical light microscopy, which is achieved by using a pinhole (pinhole) located in the image plane and limiting the flow of background scattered light emitted not from the focal plane of the lens. This allows a series of images to be obtained at different depths of the focal plane within the sample (so-called optical sectioning of the sample in depth), and then to reconstruct a three-dimensional image of the sample from these series.

On Figure 1 illustrated a schematic representation of CLSM. At first an excitation laser beam goes through a beam splitter towards scanning mirrors, which are motorized to deflect a beam to perform scanning. Microscope objective lens collect a deflected beam and focus it at the sample, that responds with emission of light of a different wavelength. This light is collected again by the objective lens and moves back through the scanning mirrors towards a beam splitter, where emitted light is reflected to a pinhole, which filters out all the out of plane light. In the end emitted light is exposed to the confocal detector, which registers light and converts it to electrical signal, stored in computer.

A picture containing chart

Description automatically generated

Figure 1 Confocal Laser Scanning Microscope principal scheme.

During operation, CLSM can work in three modes:

1. Line scan. Laser is deflected only in one dimension . This method allows to monitor rapid processes, due to low amount of recorded information. Used when speed is more important than spatial information
2. 2D scan. Laser is deflected in two dimensions . This method allows to capture more spatial information by sacrificing the acquisition time. Used when spatial information is more important than temporal.
3. Volumetric scan. Laser is deflected in three dimensions and performs complete Z-stack acquisition . Only used when a time component is negligible, and a sample is static.

## Aims of Image Analysis

Image analysis involves processing images into fundamental components to extract meaningful information. It may involve tasks such as finding shapes, detecting edges, removing noise, counting objects, texture analysis etc.

In this Thesis only the segmentation procedure will be explained.

## Machine learning in image processing

Machine learning is a set of sophisticated mathematical operations performed on data to receive a meaningful result from it. These algorithms are conventionally generalized in form of pattern recognition pipeline (Figure 2). At first the data is acquired using any type of electronical device such as a camera, microphone, or a microscope. Then this data is stored and preprocessed. In preprocessing step data is filtered, enhanced, and prepared for further steps. Next goes a feature extraction, which extracts representative features from data using a set of mathematical operations. These features can represent a simplified version of original data or can create new data, that allows for algorithms to find intra-data correspondences. At a later stage these features are used for so called learning or training step. During training Algorithm will try to find the best possible split to classify the data with minimal error, based on extracted features.

Graphical user interface, diagram

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Figure 2 pattern recognition pipeline [3]

These algorithms in image processing are conventionally divided in two groups: Classical and Deep Learning approaches. Difference between those groups can be compared using the pattern recognition pipeline (Figure 2):

* Classical machine learning approaches follow this pipeline. They require small amount of data and small computational costs. Lack on generalization and precision.
* Deep Learning approaches bypass part of this pipeline by combining feature extraction with classification. There are no predefined feature extraction procedures in neural networks, and these procedures are estimated, during the training process. They require huge amount of human labeled data, high computational costs, and time. They are good at generalization and most of the state-of-the art methods now are using neural networks.

Deep Learning approaches require gigantic amount of human labeled data. Due to that it is always preferable to find a way to minimize the labeling time from human because it is tedious and expensive. For that reason, it is important to assist human operator with labeling task. One of the promising methods is to use classical machine learning approaches like Random Forests for easier data labeling.

## Decision Tree

Before speaking about Random Forest, it is important to explain decision tree classifier (DTC). Decision Trees are a non-parametric supervised learning method used for [classification](https://scikit-learn.org/stable/modules/tree.html#tree-classification) and [regression](https://scikit-learn.org/stable/modules/tree.html#tree-regression). The goal is to create a model that predicts the value of a target variable by learning simple decision rules inferred from the data features. The selection process can be described as a sequence of binary selections corresponding to the traversal of a tree structure. One limitation of decision trees is that the division of input space is based on hard splits in which only one model is responsible for making predictions for any given value of the input variables.

Diagram

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Figure 3 Classification Tree example

Tree model consists of nodes and each node will ask a true false question about one of the features () (Figure 3). And in response to this question, the data is split into two subsets. These subsets then become the input to two child nodes that are added to the tree. And the goal of the question is to unmix the labels as proceeding down. Or in other words, to produce the purest possible distribution of the labels at each node. The quantification of a split uncertainty at a single node can be achieved using a metric called Gini impurity:

– number of classes, – probability of correctly classifying class . And we can quantify how much a question reduces that uncertainty using a concept called information gain. Given that question, we'll recursively build the tree on each of the new nodes. We'll continue dividing the data until a limit called a tree height will occur, at which data is no longer divided and a class is assigned based on the majority of samples present in the last subset of points. This height is set up manually to prevent a tree from overfitting.

A single classification tree is a powerful algorithm that lacks on generalization and prone to overfitting. Ensembling of multiple classification trees is a common strategy to achieve higher generalization and accuracy.

## Random forest

Random forest is a classical machine learning method for data classification. It is based on ensembling of multiple Decision Trees and “decides” based on the majority voting of all decision trees. Each tree is trained on a random subset of data, which leads to a random set of uncorrelated trees. This algorithm is used for classification of pixels for annotation of digital stacks.

## Feature extraction

Intensity values on their own are a weak data representation, they do not to represent the neighborhood regions, also they cannot be used with RF, because it will only divide the image dataset based on intensity threshold, which is ineffective. Spatial information is much more valuable and has a tendency for better generalization. How to blend the information from a neighborhood region and extract important information about it? It can be done using a mathematical operation, called convolution.

### Convolutions

Convolution is a mathematical operation, performed on two functions, that produces a third one, that expresses how a shape of one function will modify the shape of another one:

Once used for discrete domain, it must be reformulated for image stack application like:

Here are the pixel coordinates in image stack and are the pixel-wise iterators. From these two definitions it is defined, that a single pixel intensity is a function of the pixel’s neighborhood and a new function, called kernel.

### Feature sets

In image processing different types of functions or kernels are convolved with image to obtain different spatial effects:

1. Box kernel – spatial linear filter, each pixel in the resulting image has a value averaged of its neighborhood pixels.   
   ,   
   where is a size of a box kernel. This kernel blurs the image.
2. Gaussian kernel – , where is a standard deviation. Blur the image with an effect of a circular aperture – the kernel has a radial symmetry.
3. Sobel operator – used in image processing for edge detection. Composed of two operations: Finding the spatial x and y image derivatives and combining their results with
4. Difference of Gaussians – a kernel composed as a difference of two different gaussian kernels is a close approximation of and is used as a replacement for – blurring and edge detection procedure, due to decreased computational cost.
5. Median filter – nonlinear filter, that assigns the median intensity value of the neighborhood pixel area to a given pixel. Allows to minimize a presence of high frequency noise.

All these kernels with different parameters are used to create image features, necessary for preserving the neighborhood correspondence and extraction of important features from it, like edges, textures, and shapes.

# Methods

## Weka segmentation plugin

Open-source FIJI (based on ImageJ) has a built-in plugin for human aided image segmentation, using random forests. This plugin called Weka Segmentation. It utilizes the random forest approach together with the feature extraction described in the previous chapters. It can be accessed from the toolbar Plugins menu -> Segmentation -> Trainable Weka segmentation 3D.

A screen shot of a map

Description automatically generated with medium confidence

Figure 4 Example image of the Weka Segmentation plugin

Usage of this plugin is simple, but some preparations are required for the given task. Setup requires:

1. Select number of classes: it is necessary to segment 3 classes – Background, Cells, Cell borders.
2. Select a set of the feature types: these features will be used for classification by a RF. It should consist of Gaussian blur and Difference of Gaussian filters with the sigma range of 1.0 - 8.0.

## Statistical analysis

# Results

Random forest is a suitable semantic segmentation tool for 3 dimensional images. More filters are used for classification the more stable and reliable result can be acquired. Generalization gets higher (model does not overfit) and precision rises. On the other hand, the memory consumption rises too together with the computation time required for feature computation. To increase processing time main goal is to find the golden ratio between computation time and model precision. For smaller stacks, more different features can be computed in comparison to larger stacks with better precision and speed. For larger stacks it is important to select the most adequate feature set as a precision trade-off.

Segmentation result can be seen on the Figure 5. It was slightly filtered after classification, using median filter of size 1 and cancellation of all blobs with size < 10 pixels.

A picture containing text, close

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Figure 5. Examples of immune cells segmentation using Random Forest classifier

# Discussion

Performance of a Random Forest classifier assumed to be suitable for this application. But how differ it in comparison with deep learning approach? The DL approach will require 100s of completely hand-labeled images, powerful workstation, and hours of training. The preliminary result can be observed only after a day. But segmentation of unseen data can be done relatively fast, with good generalization and accuracy. With RF approach you can get the stack-wise result in less than a minute, depending on the stack size and number of features. The amount of data required can be equal to 3-4 labeled cells on 1 slice! The rest it generalizes itself. But with simplicity comes underperformance – RF lacks on generalization for different images. The capacity of this classifier is limited, and features are not optimized for application and are selected mostly intuitively. DL approach on the other hand optimize a huge number of feature extractors to be most efficient for selected application and hence performs better.

RF can be used as a labeling aid for DL dataset creation

# Conclusion

Human manual labeling of 3d microscopic images is a tedious task. It requires a great amount of time and money to be invested. This routine can be simplified using machine learning algorithms. Human aided software might label data with higher speed then conventional methods. And it requires less training time in comparison to deep-learning methods. Common open-source software like FIJI provides users with a conventional tool to segment 3d images and to classify the respective pixels.

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# Appendix

Curriculum vitae

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Erklärung

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I confirm that I have written this thesis without any external help and

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other examination board and has not been previously accepted as part of a

exam for a qualification.

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Acknoledgement